

## TwoNonIsomorphicExtensions

Let  $R := \mathbb{Q}[x, y, z]$ . In this example we want to study two non-equivalent extensions  $0 \rightarrow K \rightarrow M \rightarrow L \rightarrow 0$  and  $0 \rightarrow K \rightarrow N \rightarrow L \rightarrow 0$  with  $K$  a torsion module and  $L$  a torsion free module. Our goal is to use the notion of functor to reveal that these extensions are not only non-equivalent but also non-isomorphic. For this we define two functors  $F_M$  and  $F_N$  and study their behavior when applied to complexes. Concretely, we apply  $F_M$  resp.  $F_N$  to  $0 \rightarrow K \rightarrow M \rightarrow L \rightarrow 0$  which we refer to as

$$S : 0 \rightarrow K \xrightarrow{\alpha_1} M \xrightarrow{\alpha_2} L \rightarrow 0.$$

In the following we consider

$$F_Q = \text{Ext}(1, -, Q) = \text{Ext}^1(-, Q) = R^1 \text{Hom}_R(-, Q)$$

```
> restart;
> with(Involutuve): with(homalg):
Specify the homalg-table of the ring package Involutuve:
> RPI:='Involutuve/homalg';
```

$$RPI := \text{Involutuve}/\text{homalg}$$

Use the ring package **Involutuve** as the default ring package:

```
> 'homalg/default':=RPI;
```

$$\text{homalg/default} := \text{Involutuve}/\text{homalg}$$

We force the Maple ring package **Involutuve** to use the external program JB, which is a C++ implementation of the involutive division algorithm:

```
> InvolutuveOptions("C++");
```

Define the ring  $R = \mathbb{Q}[x, y, z]$ :

```
> var:=[x,y,z];
```

$$var := [x, y, z]$$

The two presentation matrices  $M$  and  $N$ :

```
> MM:=matrix([[x*z, z*y, z^2, 0, 0, y], [0, 0, 0, z^2*y-z^2, z^3, x*z], [0, 0, 0, z*y^2-z*y, z^2*y, x*y], [0, 0, 0, x*z*y-x*z, x*z^2, x^2], [-x*y, -y^2, -z*y, x^2*y-x^2-y+1, x^2*z-z, 0], [x^2*y-x^2, x*y^2-x*y, x*z*y-x*z, -y^3+2*y^2-y, -z*y^2+z*y, 0]]);
```

$$MM := \begin{bmatrix} xz & zy & z^2 & 0 & 0 & y \\ 0 & 0 & 0 & z^2y - z^2 & z^3 & xz \\ 0 & 0 & 0 & zy^2 - zy & z^2y & xy \\ 0 & 0 & 0 & xzy - xz & xz^2 & x^2 \\ -xy & -y^2 & -zy & x^2y - x^2 - y + 1 & x^2z - z & 0 \\ x^2y - x^2 & x^2y^2 - x^2y & xzy - xz & -y^3 + 2y^2 - y & -zy^2 + zy & 0 \end{bmatrix}$$

```
> NN:=matrix([[x*y, y^2, z*y, 0, 0, z], [0, 0, 0, z*y^2-z*y, z^2*y, x*z], [x^2*z, x*z*y, x*z^2, -z^2*y+z^2, -z^3, 0], [0, 0, 0, y^3-2*y^2+y, z*y^2-z*y, x*y-x], [0, 0, 0, x^2*y-x^2-y+1, x^2*z-z, y], [x^3, x^2*y, x^2*z, -x*z*y+x*z, -x*z^2, 0]]);
```

$$NN := \begin{bmatrix} xy & y^2 & zy & 0 & 0 & z \\ 0 & 0 & 0 & zy^2 - zy & z^2y & xz \\ x^2z & xzy & xz^2 & -z^2y + z^2 & -z^3 & 0 \\ 0 & 0 & 0 & y^3 - 2y^2 + y & zy^2 - zy & xy - x \\ 0 & 0 & 0 & x^2y - x^2 - y + 1 & x^2z - z & y \\ x^3 & x^2y & x^2z & -xzy + xz & -xz^2 & 0 \end{bmatrix}$$

The two modules  $M := \text{coker} \left( R^{1 \times 6} \xrightarrow{M} R^{1 \times 6} \right)$  and  $N := \text{coker} \left( R^{1 \times 6} \xrightarrow{N} R^{1 \times 6} \right)$ :

```
> M:=Cokernel(MM,var);
```

```

M := [[[1, 0, 0, 0, 0, 0] = [1, 0, 0, 0, 0, 0], [0, 1, 0, 0, 0, 0] = [0, 1, 0, 0, 0, 0],
[0, 0, 1, 0, 0, 0] = [0, 0, 1, 0, 0, 0], [0, 0, 0, 1, 0, 0] = [0, 0, 0, 1, 0, 0],
[0, 0, 0, 0, 1, 0] = [0, 0, 0, 0, 1, 0], [0, 0, 0, 0, 0, 1] = [0, 0, 0, 0, 0, 1]], [
[xz, zy, z^2, 0, 0, y], [0, 0, 0, z^2 y - z^2, z^3, xz], [0, 0, 0, z y^2 - z y, z^2 y, xy],
[0, 0, 0, x z y - x z, x z^2, x^2], [x^2 z, x z y, x z^2, 0, 0, xy],
[-xy, -y^2, -zy, x^2 y - x^2 - y + 1, x^2 z - z, 0],
[x^2 y - x^2, x y^2 - x y, x z y - x z, -y^3 + 2 y^2 - y, -z y^2 + z y, 0],
[0, 0, 0, z y - z, z^2, x^3 - y^2]], "Presentation",
 $\frac{3s^2}{1-s} + \frac{2s}{1-s} + \frac{2}{(1-s)^2} + \frac{3}{(1-s)^3} + \frac{2s^2}{(1-s)^2} + s^2 + s + \frac{1}{1-s} + \frac{s}{(1-s)^2}$ ,
[34, 14, 3]]
> N:=Cokernel(NN,var);

N := [[[1, 0, 0, 0, 0, 0] = [1, 0, 0, 0, 0, 0], [0, 1, 0, 0, 0, 0] = [0, 1, 0, 0, 0, 0],
[0, 0, 1, 0, 0, 0] = [0, 0, 1, 0, 0, 0], [0, 0, 0, 1, 0, 0] = [0, 0, 0, 1, 0, 0],
[0, 0, 0, 0, 1, 0] = [0, 0, 0, 0, 1, 0], [0, 0, 0, 0, 0, 1] = [0, 0, 0, 0, 0, 1]], [
[xy, y^2, zy, 0, 0, z], [0, 0, 0, z y^2 - z y, z^2 y, xz], [x^2 z, x z y, x z^2, -z^2 y + z^2, -z^3, 0],
[0, 0, 0, y^3 - 2 y^2 + y, z y^2 - z y, xy - x], [0, 0, 0, x^2 y - x^2 - y + 1, x^2 z - z, y],
[x^2 y, x y^2, x z y, 0, 0, xz], [x^3, x^2 y, x^2 z, -x z y + x z, -x z^2, 0],
[0, 0, 0, x y^2 z - x z y, x y z^2, x^2 z], [0, 0, 0, 0, 0, x^3 z - z y^2 - x z],
[0, 0, 0, x y^3 - 2 x y^2 + x y, x y^2 z - x z y, x^2 y - x^2],
[0, 0, 0, 0, 0, x^3 y - x^3 - y^3 - x y + y^2 + x]], "Presentation",
 $\frac{3s}{1-s} + \frac{2}{(1-s)^2} + 2s^2$ 
+  $\frac{3}{(1-s)^3} + \frac{2s^2}{(1-s)^2} + \frac{s^2}{1-s} + s^3 + \frac{1}{1-s} + \frac{s^3}{1-s} + \frac{s}{(1-s)^2}$ , [51, 17, 3]]

```

The torsion submodule  $K := t(M)$  of  $M$  (and  $N$ ):

```
> K:=TorsionSubmodule(M,var);
```

```

K := [[[1, 0, 0] = [0, 0, 0, 0, 0, 1], [0, 1, 0] = [0, 0, 0, y - 1, z, 0], [0, 0, 1] = [x, y, z, 0, 0, 0]
], [[y, 0, z], [0, -z y, xz], [xz, z^2, 0], [0, -y^2 + y, xy - x], [xy, z y, 0], [0, x^2 - 1, -y],
[x^2, x z, 0]], "Presentation",  $s + \frac{1}{1-s} + \frac{s}{(1-s)^2} + \frac{2}{(1-s)^2} + \frac{s}{1-s}$ , [7, 3, 0]]

```

The embedding  $0 \rightarrow K \xrightarrow{\alpha_1} M$ :

```
> alpha1:=TorsionSubmoduleEmb(M,var);
```

$$\alpha_1 := \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & y - 1 & z & 0 \\ x & y & z & 0 & 0 & 0 \end{bmatrix}$$

The torsion free factor  $L := M/K = M/t(M)$  of  $M$  (and  $N$ ):

```
> L:=Cokernel(alpha1,M,var);
```

```

L := [[[1, 0, 0, 0, 0] = [1, 0, 0, 0, 0, 0], [0, 1, 0, 0, 0, 0] = [0, 1, 0, 0, 0, 0],
[0, 0, 1, 0, 0, 0] = [0, 0, 1, 0, 0, 0], [0, 0, 0, 1, 0, 0] = [0, 0, 0, 1, 0, 0],
[0, 0, 0, 0, 1, 0] = [0, 0, 0, 0, 1, 0]], [[0, 0, 0, y - 1, z], [x, y, z, 0, 0, 0]], "Presentation",
 $\frac{2}{(1-s)^2} + \frac{3}{(1-s)^3}$ , [5, 5, 3]]

```

The natural epimorphism  $M \xrightarrow{\alpha_2} L \rightarrow 0$ :

```
> alpha2:=CokernelEpi(alpha1,M,var);
```

$$\alpha_2 := \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The short sequence  $S : 0 \rightarrow K \xrightarrow{\alpha_1} M \xrightarrow{\alpha_2} L \rightarrow 0$  is exact:

```
> IsShortExactSeq(K,alpha1,M,alpha2,L,var);
                                         true
```

The functor  $\text{Ext}_R^1(-, N)$  applied to the short exact sequence  $S$ :

```
> coseqN:=ExtOnSeqs(1,N,[alpha2,alpha1],[L,M,K],var):
```

This says that the map  $\text{Ext}_R^1(L, N) \xrightarrow{\text{Ext}_R^1(\alpha_2, N)} \text{Ext}_R^1(M, N)$  is not injective, i.e. that the connecting homomorphism  $\text{Hom}_R(K, N) \xrightarrow{\delta^0} \text{Ext}_R^1(L, N)$  is non-trivial:

```
> IsShortExactSeq(op(MakeCoseq(coseqN)),var,"VERBOSE");
```

“homs” = *true*, “cmps” = *true*, “defs” =

$$[[[1 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}], [z, y, x], \text{“Presentation”}, 1, [0, 0, 0]], \text{true}, \text{true}]$$

The functor  $\text{Ext}_R^1(-, M)$  applied to the short exact sequence  $S$ :

```
> coseqM:=ExtOnSeqs(1,M,[alpha2,alpha1],[L,M,K],var):
```

Whereas the resulting sequence  $\text{Ext}_R^1(S, M)$  is again exact. In particular, the connecting homomorphism  $\text{Hom}_R(K, M) \xrightarrow{\delta^0} \text{Ext}_R^1(L, M)$  is trivial, i.e. the zero map:

```
> IsShortExactSeq(op(MakeCoseq(coseqM)),var,"VERBOSE");
```

*true*

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## REFERENCES

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